



ROBOTS PRODUCT OVERVIEW

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FANUC ROBOTS **PRODUCT OVERVIEW**

Application Icon Key

Assembly ARC Welding





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Dena	erie	S					
Robot Model	Max. Payload (kg)	Reach (mm)	Mass (kg)	Axes	Floor	Angle	Invert
M-1 <i>i</i> A/0.5A	0.5 (1)*1	280	23* ²	6	✓	\checkmark	\checkmark
M-1 <i>i</i> A/0.5AL	0.5 (1)*1	420	26*²	6	\checkmark	\checkmark	\checkmark
M-1 <i>i</i> A/0.5S	0.5 (1)*1	280	20*²	4	\checkmark		\checkmark
M-1 <i>i</i> A/0.5SL	0.5 (1)*1	420	23*²	4	✓		✓
M-1 <i>i</i> A/1HL	1	420	21* ²	3	\checkmark		\checkmark
M-2 <i>i</i> A/3S	3	800	130	4			
M-2 <i>i</i> A/3SL	3	1130	130	4			
M-2 <i>i</i> A/6H	6	800	125	3		nted	
M-2 <i>i</i> A/6HL	6	1130	125	3		Ceiling Mounted	
M-3 <i>i</i> A/12H	12	1350	155	3		eiling	
DR-3 <i>i</i> B/8L	8	1600	170	4		ů	
DR-3 <i>i</i> B/6 STAINLESS	6	1200	250	4			

*1) Optional higher payload *2) With stand

	SCARA	Ser	ies						
	Robot Model	Max. Payload (kg)	Reach (mm)	Mass (kg)	Axes	Floor	Wall	Invert	Featu SR
	SR-3 <i>i</i> A	3	400	19	4	✓	\checkmark		
	SR-3 <i>i</i> A/H	3	400	17	3	\checkmark	\checkmark		
	SR-3 <i>i</i> A/C	3	400	21	4	\checkmark	✓		
-	SR-3iA/U	3	350	27	4			\checkmark	
	SR-6 <i>i</i> A	6	650	30	4	\checkmark	\checkmark		
	SR-6 <i>i</i> A/H	6	650	28	3	\checkmark	\checkmark		•
-	SR-6iA/C	6	650	32	4	✓	\checkmark		•••••
	SR-12 <i>i</i> A	12	900	53	4	\checkmark	\checkmark		•
	SR-12 <i>i</i> A Environmental Option	12	900	56	4	✓	√		
1	SR-20 <i>i</i> A	20	1100	64	4	\checkmark	\checkmark		• • • • • • • • • • •
	SR-20iA Environmental Option	20	1100	67	4	✓	✓		•
r								_	

Feature Spotlight: **SR-3***i***A**/**U**

The new SR-3iA/U ceiling mount SCARA robot features a full 360-degree work envelope with no dead zones, meaning the robot can access any point within its reach.

Featured Model SR-20*i*A



Featured Model

DR-3*i*B/6 STAINLESS

LR Mate Series

R B Q R Max. Reach Mass Save August Mass Reach Mass Reach Unit Reach Mass Save August Mass Reach Robot Model Payload 4 550 20 6 ✓ ✓ ER-4iA 4 550 20 6 🗸 🗸 🗸 LR Mate 200*i*D/4S LR Mate 200*i*D 7 717 25 6 🗸 🗸 🗸 🚥 7 717 24 5 🗸 🗸 🗸 LR Mate 200*i*D/7H 7 717 25 6 🗸 🗸 🗸 LR Mate 200*i*D/7C LR Mate 200*i*D/7WP 7 717 25 6 🗸 🗸 🗸 LR Mate 200*i*D/7L 7 911 27 6 🗸 🗸 🗸 LR Mate 200*i*D/7LC 7 911 27 6 √ √ √ LR Mate 200*i*D/14L 14 ⁹¹¹ (820)^{*1} 27 6 ✓ ✓ ✓

*1) For LR Mate 200*i*D/14L, 911mm reach is available when load capacity is <12kg

Featured Model LR Mate 200*i*D

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Featured Model

5.

Featured Model

M-10*i*D/12

LR-10*i*A/10

R D D S

LR-10 Series

Max. Reach Mass Save Axes (mm) (kg) Robot Model Payload <mark>′ LR-10*i*A/10</mark> 10^{*1} 1101 46 6 ✓ ✓ ✓ ✓

Feature Spotlight: LR-10*i*A/10

A compact 6-axis robot designed for machine tending, as well as a variety of picking applications found in the warehousing and logistics markets. This robot is an ideal solution for companies with limited floor space, as its slim arm fits into machine tools to load and unload parts.

Weighing just 46 kg, the LR-10*i*A/10 robot mounts to the floor, upside down, or on an angle. It is also very easy to mount the robot to an AGV or other mobile platform to accommodate a variety of repetitive tasks or automate machines that are standing idle.

*1) Payload can be up to 13kg with restricted envelope.

M-10 Series

	Robot Model	Max. Payload (kg)	Reach (mm)	Mass (kg)	Axes	Floor	Angle	taction
	M-10 <i>i</i> D/8L	8	2032	180	6	\checkmark	\checkmark	v
	M-10 <i>i</i> D/10L	10	1636	150	6	\checkmark	\checkmark	v
,	M-10 <i>i</i> D/12	12	1441	145	6	\checkmark	\checkmark	v
	M-10 <i>i</i> D/16S	16	1103	145	6	\checkmark	\checkmark	٧

Feature Spotlight: M-10*i*D/12

FANUC M-10iD/12 offers the highest speed and precision in its class. A sleek and lightweight design features internal cable routing and a curved J2 arm minimizing interference with work pieces and fixtures, and maximizing productivity. The robot has a long reach and stroke - including the backflip region – making it easy to apply even in tight workspaces.

M-20 Series

Robot Model	Max. Payload (kg)	Reach (mm)	Mass (kg)	Axes	Floor	Angle	Invort
M-20 <i>i</i> B/25	25	1853	210	6	\checkmark	\checkmark	V
M-20 <i>i</i> B/25C	25	1853	210	6	\checkmark	\checkmark	V
M-20 <i>i</i> B/35S	35	1445	205	6	\checkmark	\checkmark	v
M-20 <i>i</i> D/12L	12	2272	250	6	\checkmark	\checkmark	v
M-20 <i>i</i> D/25	25	1831	250	6	\checkmark	\checkmark	v
M-20 <i>i</i> D/35	35	1831	250	6	\checkmark	√	V

Feature Spotlight: M-20*i*B/25C

A six-axis robot for handling products in a wide range of industries, including cleanroom environments. It offers a rigid and compact design with a sealed structure (integrated utilities and motors), and a rear or bottom exit for cables. The entire robot is rated IP67, allowing it to withstand harsh environments.



Robot Model Max. (kg) Reach (kg) Mass (kg) No No </th <th>ARC Mate Serie</th> <th>s</th> <th></th> <th>M-7</th> <th>10 Ser</th> <th>ies</th> <th></th> <th></th> <th>(B)</th> <th></th>	ARC Mate Serie	s		M-7	10 Ser	ies			(B)	
ARC Mate S0/D/T 7 911 27 6 7 7 ARC Mate 100D 12 1441 15 6 7 7 ARC Mate 100D/T0L 10 163 150 6 7 7 ARC Mate 100D/T0L 10 163 150 6 7 7 ARC Mate 100D/T0L 10 163 150 6 7 7 ARC Mate 120D/T2L 12 220 180 6 7 7 ARC Mate 120D/T2L 12 2272 250 6 7 7 M-700/72L 12 2173 540 6 7 7 M-700/72L 12 3173 540 6 7 7 M-700/72L 12 3173 540 6 7 7 CRX-10A Murant 10 124 6 7	Robot Model Payload (mm)	Mass (kg)	Invert	Robot M	del Payloa			Axes Floor	Angle	Invert
ARC Mate 100.D/10L 10 1436 190 6 7 7 ARC Mate 100.D/2L 8 2032 190 6 7 7 ARC Mate 120.D 22 193 6 7		27 6 🗸 🗸	V	M-710 <i>i</i> C	12L 12	3123	540	6 🗸	√	\checkmark
ARC Mate 100/0/26L 8 2032 180 6 7 7 ARC Mate 120/0/22 2 1831 230 6 7 7 7 7 7 7 6 7 7 ARC Mate 120/0/22 12 2222 280 6 7 7 7 7 7 6 7 7 7 ARC Mate 120/0/12 12 2222 280 6 7 8 8	ARC Mate 100 <i>i</i> D 12 1441	145 6 🗸 🗸	1	M-710 <i>i</i> C	20L 20	3110	540	6 🗸	\checkmark	✓
ARC Mate 12010 25 1831 250 4 7 <th7< th=""> 7 7</th7<>	ARC Mate 100 <i>i</i> D/10L 10 1636	150 6 🗸 🗸		M-710 <i>i</i> C/	20M 20	2582	530	6 🗸	√	\checkmark
MRK Mate 120/0/12L 12 227 250 6 V V M-2018/25 (metre) 25 1833 210 6 V V CRX-101A/L metre) 12 3123 540 6 V V CRX-101A/L metre) 10 1249 40 6 V V CRX-101A/L metre) 10 1249 6 V	ARC Mate 100 <i>i</i> D/8L 8 2032	180 6 🗸 🗸		M-710 <i>i</i> C/	45M 45	2606	570	6 🗸	\checkmark	✓
M-20/B/25 we krol 25 1853 210 6 V V M-20/B/25 we krol 25 1853 210 6 V V M-710/C/12L (we krol 12 3123 540 6 V V CRX-101/AL meter 10 1249 40 6 V V V CRX-101/AL meter 10 1188 40 6 V	ARC Mate 120 <i>i</i> D 25 1831	250 6 🗸 🗸	✓	н 🔶 🛧 М-710 <i>і</i> 0	/50 50	2050	560	6 🗸	✓	√
Mr.710iC/12L Irevant 12 3123 540 6 √ √ CRX-101A/ Irevant 10 1249 40 6 √ √ √ CRX-101A/ Irevant 10 1418 40 6 √ √ √ √ √ CRX-251A 10 1418 40 6 √	ARC Mate 120 <i>i</i> D/12L 12 2272	250 6 🗸 🗸	✓	M-710 <i>i</i> C	50H 50	2003	540	5 🗸		\checkmark
CRX-10/A/L received 10 1249 40 6 V V CRX-10/A/L received 10 1418 40 6 V V CRX-10/A/L received 10 1418 40 6 V V CRX-10/A/L received 10 1418 40 6 V V CRX-10/A/L received 15 1441 25 6 V V Pestured Model Robot Model Max. Reach Mass 9 <td>M-20<i>i</i>B/25 (For Arc) 25 1853</td> <td>210 6 🗸 🗸</td> <td>🗸 🚺 🎨 🗄</td> <td>M-710<i>i</i>C</td> <td>50S 50</td> <td>1359</td> <td>545</td> <td>6 🗸</td> <td>\checkmark</td> <td>\checkmark</td>	M-20 <i>i</i> B/25 (For Arc) 25 1853	210 6 🗸 🗸	🗸 🚺 🎨 🗄	M-710 <i>i</i> C	50S 50	1359	545	6 🗸	\checkmark	\checkmark
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CRX-25/A tree set: 25 1887 135 6 7 7 911 55 6 7 7 911 55 6 7 7 911 55 6 7 7 911 55 6 7 7 911 55 6 7 7 911 55 6 7 7 911 55 6 7 7 911 55 6 7 7 911 55 6 7 7 911 55 6 7 7 911 55 6 7 7 911 55 6 7 7 911 55 6 7 7 911 55 6 7 7 911 25 6 7 7 911 25 6 7 91 95 92					i.	···· i. · · · · · · · · · · · · · · · ·		······		i
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CR-15iA revend 15 141 25 6 7 ARC Mate120/D CRX Series Image: CRX-5iA 5 994' 2 6 7 7 Robot Model Max, Payload Reach Mass 8 6 9 9 1 CRX-5iA 5 994' 25 6 7 7 CRX-10iA 10 1249'' 40 6 7 7 CRX-10iA/L 10 1418'' 40 6 7 7 CRX-20iA/L 20 1418'' 40 6 7 7 Lightweight and compact design allows for quick integration iron work area or existing sys			V X							
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CRX-20iA/L 20 1418'1 41 6 √ √ CRX-25iA 25 1889'1 135 6 √ √ CRX-25iA 25 1889'1 135 6 √ √ Feature Spotlight: CRX-10iA/L Image: Compact design allows for quick integration into any work area or existing system. CRX is easy to use and teach points using lead-through programming and a tablet interface with drag-and-drop icons. Featured Model Max. Payload Reach Mass 80 10 80 10 1115 6 √ 10 1115 6 √ 10 1115 6 √ 10 1115 6 √ 10 1115 6 √ 10 1115 6 √ 10 1115 6 √ 10 1115 6 √ 10 1115 6 √ 10 1115 6 √ 10 1115 6 √ 10 1115 6 √ 10 1115 6 √ 10 1115 6 √ 10 1115 6 √ 10 1115 6 <	Robot Model Payload (mm) (kg	a) Ax Ax	8 9 8 9 8 8 8 2 	Robot	Model Pay (ax. rload (m kg)	m) (k	(g) Ă		
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Collaborative Series (2040 (1120) 6 ✓	Robot ModelMax. Payload (kg)Reach (mm)Max (kg)CRX-5iA5994*125CRX-10iA101249*140CRX-20iA/L101418*141CRX-25iA251889*113Feature Spotlight: CRX-10iA/LLightweight and compact design allows into any work area or existing system. C and teach points using lead-through pro	g) $\overleftarrow{\mathbf{X}}$ $\overrightarrow{\mathbf{E}}$ $\overrightarrow{\mathbf{E}}$ $\overrightarrow{\mathbf{E}}$ 56 \checkmark \checkmark \checkmark 06 \checkmark \checkmark \checkmark 06 \checkmark \checkmark \checkmark 16 \checkmark \checkmark \checkmark 356 \checkmark \checkmark \checkmark DiA/LSolution colspan="4">Colspan="4"Colspan="4">Colspan="4"Col		Robot R-1000 R-1000 R-1000 R-1000 R-1000 R-1000 R-2000 R-2000	Model Pay A/80F 4 A/80H 4 A/100F 1 A/130F 1 A/130F 1 C/100P 1 C/125L 1	ax. (load) kg) Rei (m 30 22 30 30 30 30 30 30 30 30 30 30 30 30 30 30 30 30 30 30 30 30 30 30 30 30 30 30 30 30 30	m) (k 30 62 30 62 30 63 30 64 30 65 30 67 30 7 30 7 30 7 30 7 30 7	cg) X 20 6 10 5 65 6 75 6 (ass) 6 kg) . 470 115	↓ ↓ ↓ ↓	alger Bur Bur Bur
	Robot ModelMax. Payload (kg)Reach (mm)Max. (kg)CRX-5iA5994*125CRX-10iA101249*140CRX-20iA/L101418*140CRX-25iA251889*113Feature Spotlight: CRX-10iA/LImage: CRX-20iA/L201418*141CRX-25iA251889*113Feature Spotlight: CRX-10iA/LColspan="4">Colspan="4"Colspan="4"Colspan="4"Colspan="4"Colspan="4"Colspan="4"Colspan="4"	g) $\overleftarrow{\mathbf{X}}$ $\overrightarrow{\mathbf{E}}$ $\overrightarrow{\mathbf{E}}$ $\overrightarrow{\mathbf{E}}$ 56 \checkmark \checkmark \checkmark 06 \checkmark \checkmark \checkmark 06 \checkmark \checkmark \checkmark 16 \checkmark \checkmark \checkmark 356 \checkmark \checkmark \checkmark DiA/LSolution colspan="4">Colspan="4"Colspan="4">Colspan="4"Col		Robot R-1000 R-1000 R-1000 R-1000 R-1000 R-1000 R-2000 R-2000 R-2000	Model Pay (1) (2) (2) (3) (3) (3) (4) (3) (4) (4) (4) (4) (4) (4) (4) (5) (5) (5) (6) (7) (7) (7) (7) (7) (7) (7) (7) (7) (7	ax. (load) Rei (m 30 22 30 30 30 30 30 30 30 30 30 30 30 30 30 30 30 30 30 30 30 30 30 30 30 30 30 <	m) (k 30 62 30 62 30 62 30 63 30 63 30 63 30 63 30 63 30 63 30 63 30 63 30 63 30 63 30 63 30 63 30 63 30 63 30 64 30 63 30 63 30 64 30 64 30 64 30 64 30 64 30 64 30 64 30 64 30 64 30 64 30 64 30 64 30 64 30 64 30 14 30 14	cg) X 20 6 10 5 65 6 75 6 (mass) 6 (kg) . 4700 115 0900 .	↓ ↓	alger Benerican

	Robot Model	Max. Payload (kg)	Reach (mm)	Mass (kg)	Axes	Floor	Angle	Invert
	CR-7 <i>i</i> A	7	717	53	6	\checkmark	\checkmark	\checkmark
	CR-7 <i>i</i> A/L	7	911	55	6	\checkmark	\checkmark	\checkmark
	CR-14 <i>i</i> A/L	14	911 (820)*1	55	6	\checkmark	\checkmark	\checkmark
	CR-15 <i>i</i> A	15	1441	255	6	\checkmark	\checkmark	\checkmark
<mark>۸</mark>	CR-35 <i>i</i> B	35	1831	375	6	\checkmark		

Feature Spotlight: CR-35*i*B

The strongest collaborative robot, the CR-35*i*B's ability to lift 35k - combined with its reach and safety certification - make it suitable for a large range of manual processes people have traditionally had to do alone. With built-in anti-trap protection and soft rubber skin, it is also designed to ensure workers are protected from .

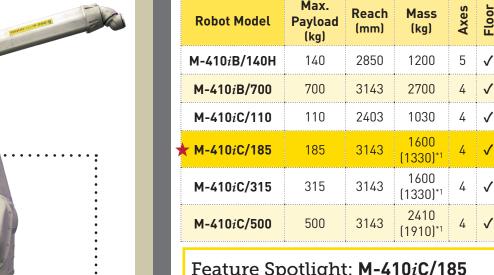


*1) For CR-14*i*A/L, 911mm reach is available when load capacity is <12kg

Paint Series

Robot Model	Max. Payload (kg)	Reach (mm)	Mass (kg)	Axes	Floor	Angle	Invert
Paint Mate 200 <i>i</i> A/5L	5	892	37	6	√	√	✓
P-40 <i>i</i> A	5	1300	110	6	\checkmark	\checkmark	\checkmark
P-50 <i>i</i> B/10L	10	1800	364	6	\checkmark	\checkmark	\checkmark
P-250 <i>i</i> B	15	2800	530	6	\checkmark	\checkmark	\checkmark
P-350 <i>i</i> A	45	2606	590	6	\checkmark	\checkmark	\checkmark
P-700 <i>i</i> B Plastic Arm	15	3150	658 (S) 665 (L)	7		Rail ount	
P-700<i>i</i>B Metal Arm	15	3200	659 (S) 667 (L)	7		Rail ount	
P-1000<i>i</i>A Plastic Arm	15	2848	700	7			✓
P-1000<i>i</i>A Metal Arm	15	2896	700	7			\checkmark

(S) Short Arm Version (L) Long Arm Version



Featured	Model
P-250	iB

M-410 <i>i</i> C/110	110	2403
★ M-410 <i>i</i> C/185	185	3143

M-410 Series

M-410 <i>i</i> B/700	700	3143	2700	4	\checkmark
M-410 <i>i</i> C/110	110	2403	1030	4	\checkmark
M-410 <i>i</i> C/185	185	3143	1600 (1330)*1	4	✓
M-410 <i>i</i> C/315	315	3143	1600 (1330)*1	4	√

Reach Mass (mm) (kg)

140 2850 1200 5 🗸

2655 1090 6 🗸

1020 6

2655 1090 6 🗸

2655 1320 6 🗸

270 3095 1590 6 RACK

165 2605 1150 6 🗸

210 3100 1350 6 🗸

2518

210 3095 1370 6 RACK

210

R-2000*i***C/210WE** 210 2450 1180 6 ✓

220

240

270

(300)*

R-2000*i***D/100FH** 100 2605 1150 6 √

R-2000*i***D/210FH** 210 2605 1150 6 ✓

*1)When accuracy and stiffness enhancement option is specified

Payload

R-2000*i***C**/210**F**

R-2000*i*C/210L

R-2000*i*C/210R

R-2000*i*C/220U

R-2000*i*C/240F

R-2000*i*C/270F

R-2000*i*C/270R

R-2000*i*D/165FH

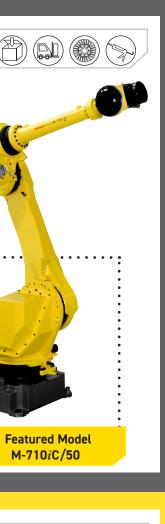
*2) With hardware and/or software option

M-410*i*C/185

Feature Spotlight: M-410*i*C/185

This compact four-axis model is designed for high speed palletizing, assembly, machining and parts transfer applications. The increased throughput makes it ideal for high volume production.

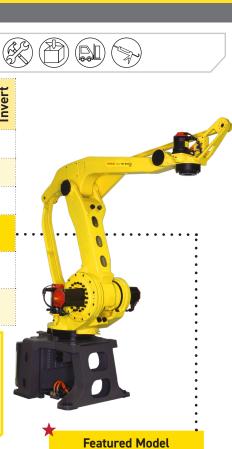
*1) Without pedestal











M-900	Seri	ies					
Robot Model	Max. Payload (kg)	Reach (mm)	Mass (kg)	Axes	Floor	Angle	Invert
M-900 <i>i</i> A/200P	200	3507	2670	6	ł	RACI	K
M-900 <i>i</i> B/280L	280	3103	1600	6	\checkmark	\checkmark	√
M-900 <i>i</i> B/330L	330	3203	1780	6	\checkmark		
M-900 <i>i</i> B/360E	360	2655	1540	6	\checkmark	\checkmark	\checkmark
M-900 <i>i</i> B/400L	400	3704	3150	6	\checkmark		
M-900 <i>i</i> B/700E	700	2832	2800	6	\checkmark		
M-800	R) @D*) (\mathcal{D}
Robot Model	Max. Payload (kg)	Reach (mm)	Mass (kg)	Axes	Floor	Angle	Invert
M-800 <i>i</i> A/60	60	2040	820	6	√		

M-1000 Series

Robot Model	Max. Payload (kg)	Reach (mm)	Mass (kg)	Axes	Floor	Angle	Invert
M-1000 <i>i</i> A	1000	3253	5300	6	\checkmark		

Feature Spotlight: M-1000*i*A

The M-1000iA is FANUC's largest robot to feature a serial link mechanism, rather than the parallel link mechanism typical of heavy payload robots. As a result, the M-1000iA has a wider range of motion in both vertical and longitudinal directions, allowing the arm to stand upright and rotate backwards, which is impossible with parallel link robots. This capability provides users with extended versatility across a wide range of handling applications.

. Featured Model M-1000*i*A

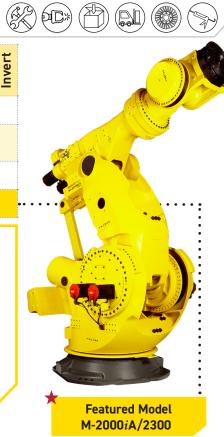
M-900*i*B/360E

M-2000 Series

Robot Model	Max. Payload (kg)	Reach (mm)	Mass (kg)	Axes	Floor	Angle	
M-2000 <i>i</i> A/900L	900	4683	9600	6	\checkmark		
M-2000 <i>i</i> A/1200	1200 (1350)*1	3734	8600	6	✓		
M-2000 <i>i</i> A/1700L	1700	4683	12500	6	\checkmark		
M-2000 <i>i</i> A/2300	2300	3734	11000	6	\checkmark		

Feature Spotlight: M-2000*i*A/2300

With its enormous payload of 2.3 metric tons, the M-2000*i*A/2300 is the biggest lifter in the M-2000 series. Ideally suited to handle material handling applications that require an even stronger wrist, this machine will easily lift and position an entire car or load bulky castings onto machine fixtures.



*1) With hardware and/or software option

iRVision 3D Vision Sensor

Version	Resolution (Pixel)	Min/Max Standoff (mm)	Field of View Dimension at Min/Max (mm)
3DV/70	870x950	Min:220 Max:276	55x70 84x92
3DV/200	950x1060	Min:355 Max:545	124x124 219x199
3DV/400	1104x950	Min:700 Max:1200	262x268 527x459
3DV/600	1104x950	Min:1300 Max:1800	576x499 804x697
3DV/1600	1104x960	Min:1500 Max:3500	1299x1223 3258x2843



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